

Application of modern ASUDD solutions on the example of Shchors street, Belgorod

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Abstract. the application of modern ASUDD solutions is considered on the example of Shchors Street in Belgorod. Field studies of traffic flows were carried out. When modeling the considered area, an increase in the load was revealed. A traffic light layout plan has been developed. It is established that due to the control of the traffic flow in the lanes with the help of ASUDD solutions, the redistribution of traffic flows in the directions is achieved.

1 Introduction

As the practice of the authors shows in the creation of traffic management projects without the use of modern solutions in the field of ASUDD, it is impossible to implement the constructive decisions taken. Significant changes in traffic intensity during the day, their redistribution as a result of the "human" factor, the creation of a priority for public transport, all this requires an instant response in the settings of traffic light objects [5, 11]. At the same time, due to the complexity of the objects, it is often necessary to implement up to 128 signal groups in one controller. Let's consider solutions in the field of ASUDD on the example of Shchors Street, Belgorod.

2 Analysis of decisions in the field of ASUDD on the example of Shchors street

One of the most difficult intersections along the entire street. Shchorsa of Belgorod is st. Gubkin [13]. At this intersection, there are both public transport stops (2 units) and regulated entry and exit from the territory of the shopping center. The traffic organization diagram is shown in Figure 1.

This ODD scheme was developed on the basis of modeling existing traffic flows using field studies carried out before the start of the reconstruction. The results of which are shown in Table 1 (rush hour - morning) [1,4].

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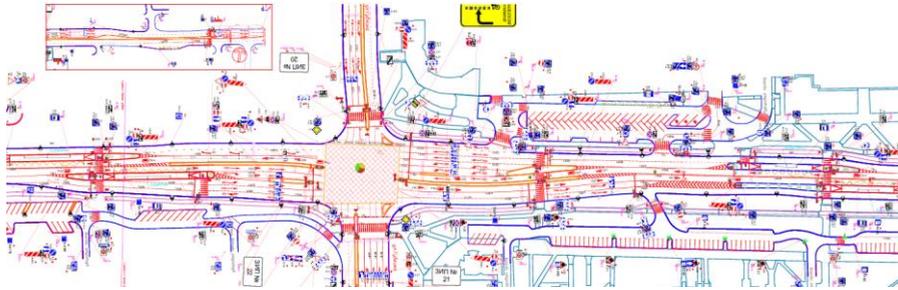


Fig. 1. ODD scheme at the intersection of st. Shchorsa - st. Gubkina

Table 1. Field research form in the morning rush hour

Direction	Shalandina Street (from the east)			Budennogo Street (from the west)			Shchorsa Street (from the north)			Shchorsa Street (from the south)		
Type of transport	units / hour											
Passenger car (units / hour)	174	332	221	221	330	226	220	334	116	448	331	778
Cargo (<2t.)	0	24	0	12	18	0	0	0	0	0	0	0
Cargo (2-6t.)	0	18	0	0	0	6	0	0	0	0	0	0
Cargo (>6t.)	0	0	0	0	0	6	0	0	0	0	0	0
Road Train	0	0	0	0	0	0	0	0	0	0	0	0
Minibus	6	0	0	0	6	6	0	18	12	12	6	0
Small bus	0	0	0	60	0	0	12	0	36	0	24	0
The bus is big	0	0	0	18	0	0	0	6	6	0	10	0
Articulated bus	0	0	0	0	0	0	0	0	0	0	0	0
Number of pedestrians	0			0			0			0		

In addition to the hour-long studies, "Infopro" transport detectors were installed on the site, which provided data on the intensity of each lane of traffic (Figure 2) [14,16].



Fig. 2. Diagram of traffic intensity on Shchorsa Street in one lane during the evening rush hour. Infopro Detector

Using the obtained data, the simulation of both the existing situation and the newly designed one for this section was carried out, which showed an increase in the load on Gubkin Street (ACCORDING to Aimsun) [2,3]. The intersection of the section is shown in Figure 3.

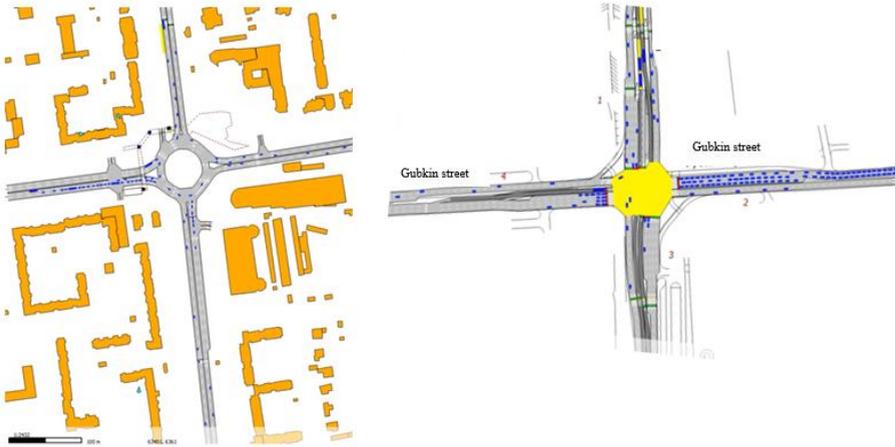


Fig. 3. Simulation models of the existing and projected intersection

Comparative analysis showed an increase in the speed of public transport by 2 times and a decrease in the speed of personal transport by 1.2 times [6,17]. Based on the obtained results of modeling IP Pashnev O. A., a plan for the placement of traffic lights was developed, shown in Figure 4 [10].

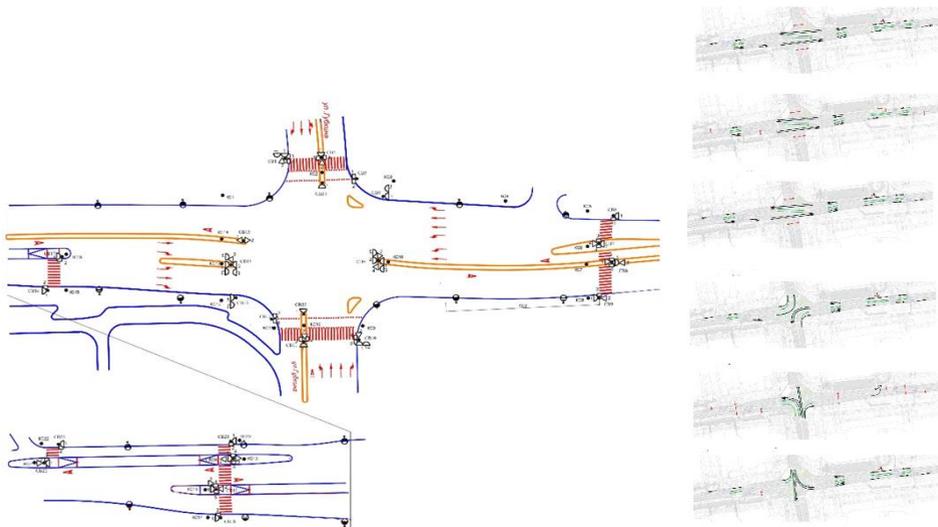


Fig. 4. Traffic light layout plan at the intersection of Shchors st. - Gubkin st.

Based on the accepted layout of the equipment, a number of requirements for controllers and software were formulated:

1. The maximum possible number of channels supported by the controller is at least 124;
2. Ability to implement coordinated adaptive management from the center;

3. The ability to connect different types of detectors.

In addition to the above requirements, an additional list of comparative data was formulated:

- * the ability to adjust the direction of movement (please briefly describe the implementation – is there a limit on the number of phases that can be recorded in the DC);

- * limit on the number of phases used in the cycle;

- * the ability to change the sequence of phases both when working on a calendar schedule, and on a call (dispatcher, call with TVP, working out a call at certain readings from the detector, etc.);

- * the number of control programs recorded in the DC itself, the technology of recording programs in the DC (directly on the site, via remote access using Ethernet, creating a library of control programs both by time of day, by days of the week and seasons). Describe the procedure for loading and selecting control programs including those using the Automated Control System APM;

- * ability to set changeable proms.clock cycles (when working with different phase sequences, using a matrix of inter-green, universal proms.Implementation of conflict control during the development of the prom.clock cycles;

- when using local adaptive control, the following parameters can be adjusted:

- minimum and maximum cycle time;

- minimum and maximum phase or direction time;

- minimum and maximum break time;

- gap reduction time;

- the time from the beginning of the phase after which the gap begins to decrease; the number of cars after which the gap begins to decrease;

- dynamic maximum (the ability to increase the maximum phase time at high load).

- if you use an adaptive control algorithm that uses a number of other parameters, please provide information about the algorithm and the parameters that an ASUDD engineer can work with [18].

List of questions about working with ASUDD:

- * the ability to create new switching programs using the phases used by the DC. There is a limit on the number of programs. The ability to use third-party resources to download new programs.

- * The ability to maintain coordinated management on the UDS site (one street or network) with adaptive management on one or more objects.

- * The ability to adjust parameters such as: the cycle time for the UDS section (minimum and maximum), the setting of the master object for which time correction is provided, the parameters for which the phase correction occurs on the slave objects with rigid or adaptive control;

- * identification of the average flow rate to create the coordination of the CO operation, including the calculation of the time shift of the leading phase assignment.

- if you use an adaptive network management algorithm that uses a number of other parameters, please provide information about the algorithm and the parameters that the ASUDD engineer can interact with

- * the ability to remotely change the configuration of the road controller with the control of the transmission of the corresponding network commands.

- * the ability to create traffic priorities, coordination, etc. along the length of the vehicle queue at the approaches to the intersection [7,9].

Based on the selection of equipment, the following types of controllers were considered, presented in Table 2 [8].

Table 2. Analysis of controllers according to the given criteria

Criteria	The controller			
	"CASCADE" (characteristics, RE)	DKSMN-S3-16, DKSMN-S3-24 (characteristics)	"KDSF SPECTRUM" (Linux) (features, RE)	KDU 3.3 N (technical description and RE)
Traffic light control algorithm				
Phase-by-phase control (including adaptive control-MGR)	yes	yes	yes	no
Formation of a promtact based on the full matrix of intergreenmatrix InterGreenMatrix	no	no	yes, up to 64 directions (signal groups)	no
Local adaptive (active) direction control	no	no	yes, multi-ring mode with direction control, control of the" break "of the flow with "intelligent" change in the trigger threshold, queue control for the time of the forbidding signal, dynamic maximum green, coordination mode, priority pass	no
Unified algorithm for local adaptive regulation	no	no	advanced Full-Actuated MultiRing controller algorithm (described by HCM2000)	no
Priority travel (priority mode)	no	no	yes, according to the arrival forecast or the activation of the call and exit detector of the zone	no
Local situational management	no	yes	yes (arbitrary logic is set by user scripts)	no
different algorithm for local adaptive control	no	delay detection; congestion detection; local, anti-congestion control	no	no
Library of SP signal plans				
Maximum number of phases	8	up to 16 phases, up to 72 directions	Not limited	no
Maximum number of phases in SP	-	-	Not limited	-
Maximum number of SP	8	32	Not limited	34
Calendar Settings	daily plan, weekly schedule	daily plan, days of the week, month	daily schedule, weekly schedule, seasonal schedule, special days of the year	daily plan, days of the week
Number of calendar entries	-	-	Not limited	34
Properties of an open information system				
Unified entities of algorithms, control parameters, and controller configurations	no	no	Yes, in the concept of a multi-ring controller (Full- Actuated multiring controller)	no
Open machine-readable configuration description format	no	no	JSON	no

As can be seen from the analysis, only the equipment of the company "RIPAS" meets the advanced requirements [15]. In addition to it, radar detectors were installed, allowing not only to monitor the traffic flow along the lanes, but also to determine the length of the queue (Figure 5).



Fig. 5. The area of coverage of the intersection with radar detectors of transport

After the opening of traffic on Shchorsa Street, the following results were obtained for the traffic flow, shown in Figures 6, 7.

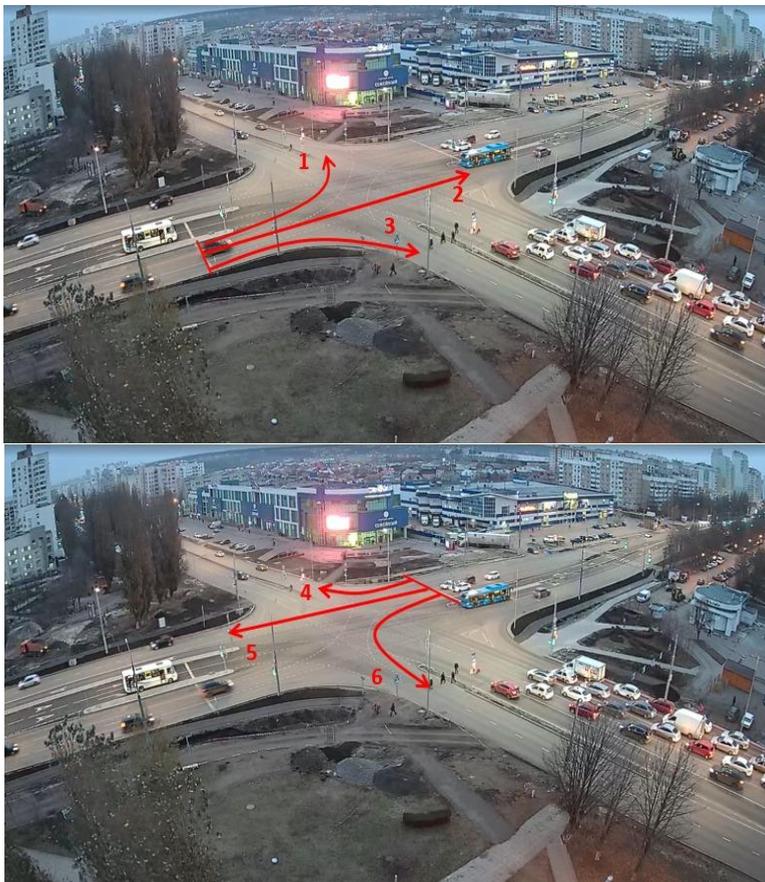


Fig. 6.

Reallocation of traffic flows in the following directions

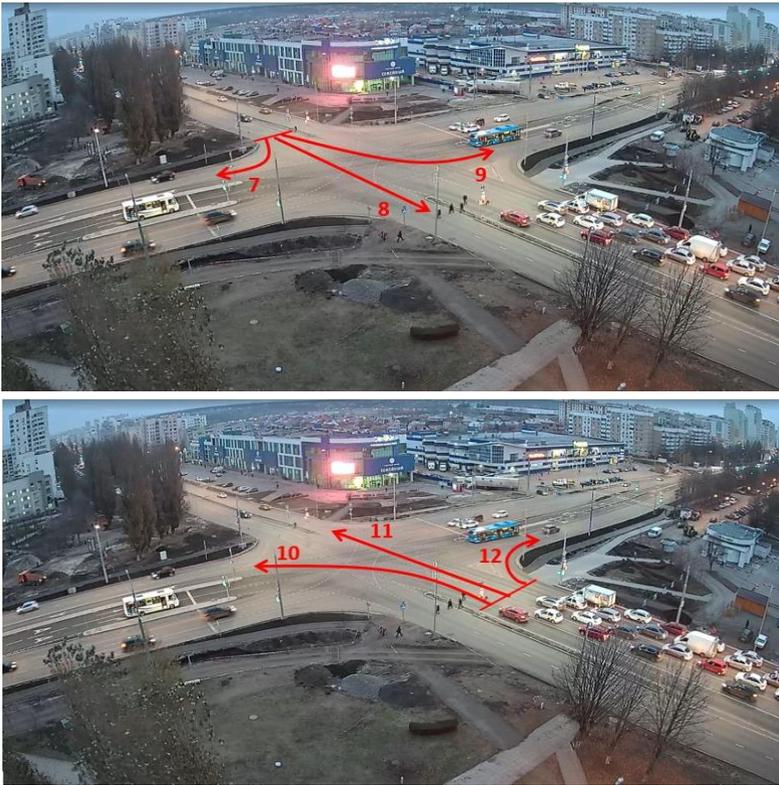


Fig. 7. Reallocation of traffic flows in the following directions

As can be seen from the presented data, the total load has not changed much, but there has been a significant redistribution of traffic flows in the directions, the graph of which is shown in Figure 8.



Fig. 8. Schedule of reallocation of traffic flows at the intersection of Shchorsa Street – Gubkin Street

Using the generated ASUDD for Shchors Street, the adaptive control system for traffic light objects was turned on, which showed the following results at different intensity settings per lane, shown in Figure 9.

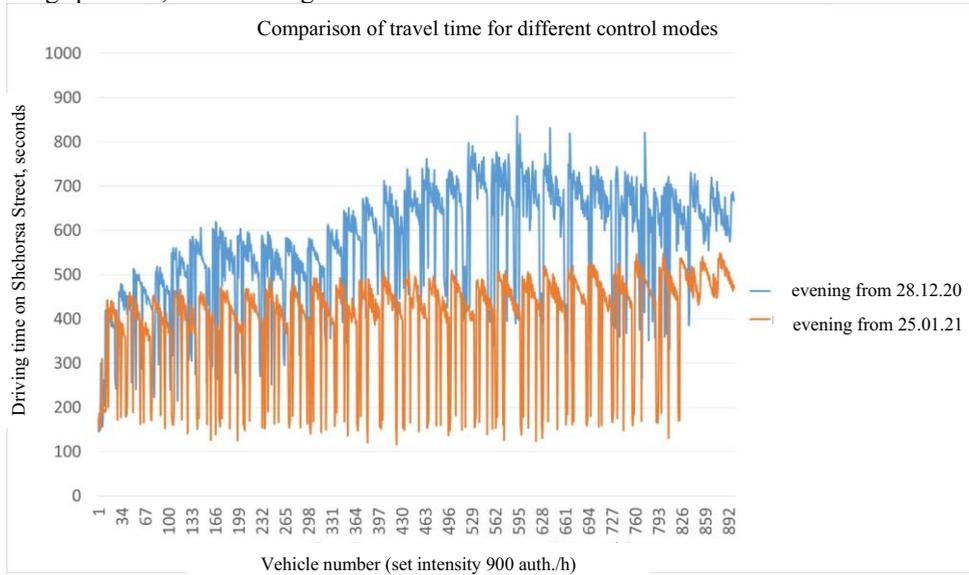


Fig. 9. Comparative work schedules of the RIPAS adaptive system on Shchors Street by travel time

3 Conclusion

To optimize traffic flows, you should use controllers and software that must meet certain requirements. The use of radar detectors allows you to monitor the traffic flow.

The adaptive system made it possible to reduce the driving time on Shchors Street relative to the basic settings of traffic lights from 650 seconds to 500 seconds, which is 23% of the basic indicator in the evening rush hour.

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