

Two-Sided assembly line balancing to minimize number of workstation with considering the relationships between tasks

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Abstract. There are many problems in assembly line. Some of the problems are assembly line reliability which relates to maintenance and unbalance workload. As a result, production line is not efficient and production plan is not fulfilled. Previous research on two-sided assembly line balancing problem has proposed improvement method by considering index relationship between tasks. There are only two factors that is taken into account in this research, they are: distance factor of the implementation of the task (distance factor) and tools used to perform the task (tool factor). Therefore, this paper aims to develops conceptual model by considering additional factors that affecting Assembly Line Tasks Consistency (ATC). The additional factors that are considered are as follow: distance factor, tool factor, motion factor, layout factor, and skill factor. The purpose of this conceptual model is to increase productivity by minimizing number of workstations. Linear combination are used to find a combination solution of a relationship between task to complete a two-sided assembly line balancing problem. Improvement of proposed assembly line are measured according to Balance Delay (BD) and Line Efficiency (LE).

1 Introduction

Two-sided assembly line is a set of tasks that must be shared and processed on a set of mated-station, each containing two opposing and opposite workstation[1]. Two-sided Assembly Line Balancing Problems (TALBPs) can be classified in a set tasks that must be divided to and processed on a set of mated-station, each containing two facing and opposite workstations. Two cooperative workers on each mated-station operate the tasks in parallel at both left and right sides. Due to the utilization of both sides, the tasks are portioned into there types, they are L-type tasks, R-type tasks, and E-type tasks. L-type tasks must be allocated to left side, R-type tasks must be allocated to right side whereas E-type task are allocated to either left and right side. Optimization criterion can be divided into three categories, there are TALBP-I with the workstation number minimization criterion, TALBP-

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II with the cycle time minimization criterion and TALBP-E with the line efficiency maximization criterion[1].

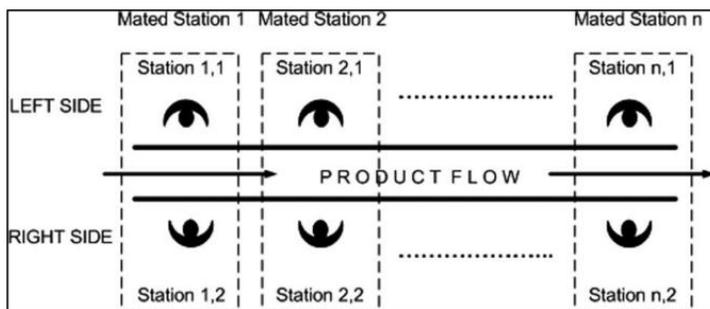


Fig. 1. Two-sided assembly line [2].

Research of [3] a developed relationship between tasks on two-sided assembly line balancing problem according to the index which he has been developed. The relationship factors only have two factors, they are distance factor of the implementation of the task (distance factor) and tools used to perform the task (tool factor). Autor of [3] suggest that in the real condition, more relationships between the tasks for assignment to each station makes assembly line become more effective. Autor of [4] suggest that this line balancing improvement is a traditional approach but it considers relevant criteria to today problem to do because easier to fix at the real object.

This research modifies factors affecting the index of task relations refers to the task relations index developed by[3]. Modification of these factors aims to improve work productivity. Productivity will essentially be related to the production system, a system in which factors such as labor, machinery, work equipment, raw materials, plant layout and so on are managed in an organized way to realize goods or services effectively and efficiently[5]. There are several additional factors that considered in this research, they are: motion factor, layout factor and skill factor. With the addition of these factors, assembly line idle time can be reduced and work becomes effective. Development of conceptual model is carried out by taken into account three performance criteria, namely: number of station, number of mated-station, and Assembly Line Tasks Consistency (ATC). Where the value on the influence factor of relation index and relationship value affecting ATC is not preliminary determined (fix) and to get the best-modified result, the linear combination is used to get the best combination of a solution. This paper aims to develop a conceptual model to minimize the number of workstations for improving line efficiency.

2 Literature Review

Two-sided assembly line balancing concept has the main goals of reducing idle time and speeding cycle time, which distinguishes only techniques in reducing idle time itself and developing algorithms used. So far there have been some idle time reduction goals with task restrictions, improved task performance in parallel and consideration of connecting task work. While on algorithm development, some researchers previously used Genetic Algorithm, Artificial Ant Colony, and Artificial Bee Colony. A summary of the references that support this research can be seen in Table 1.

Table 1. Literatur review.

Paper	Purpose	Modification	Metod	Result
Idle Times Analysis in TALBP [6]	Analising with considers idle time.	Some measure of solution are Balance Delay (BD), Line Efficiency (LE), Line Time (LT), dan Smoothness Index (SI).	Heuristic method	In TAL structure even small changes of cycle time cause changes of the structure. Additionally, some delays times between tasks be ignored at the assembly line structure.
TALB with Assignment Restriction [7]	Minimize cycle time with the assignment made more flexible dan quick to moved.	Restrictions are commonly considered in zoning restriction, distance restriction, synchronous task restriction, resource restriction, and station restriction.	Genetic algorithm and iterative first-fit rule	GA gave the result better than IFFR.
TALBP with Parallel Performance Capacity [8]	Using a new approach that allows the parallel performance of tasks.	Examine the effect of the parallel performance of paired tasks in mated stations in a TALBP problem.	Linear integer and heuristic algorithm	The algorithm were optimal for most of the small problems considered compared with the solutions of the mathematical model produced.
An Effective Discrete Artificial Bee Colony Algorithm with Idle Time Reduction Techniques for TALBP of Type-II [9]	Reduction the idle time.	Specific design tasks assignments to eliminate idle time depend on sequence.	Discrete Artificial Bee Colony (DABC)	A task assignment rule is applied to a decoding scheme that can decrease sequence-dependent idle time.
Bee algorithms for Parallel TALBP with Walking Times [10]	Introducing a two-sided assembly line problem with walking time.	Walking distance is included in the problem of parallel two-sided assembly line balancing problem.	Bees Algorithm and Artificial Bee Colony Algorithm	Walking times can not be ignored for larger assembly systems because of the long running distance between production lines.
TALB Considering The Relationships between Task [3]	Completed the two-sided assembly line balancing problem with consideration of task relation.	The task relationships introduced are distance factors and tool factors.	Simulated Annealing	Tasks that have more connections provide better opportunities to be assigned to a public station.

Paper	Purpose	Modification	Method	Result
TALB to Minimize Number of Workstation with Considering The Relationship Between Task (Dina Rachmawaty – Next Reserch)	Two-sided assembly line to minimize workstation with consideration of task relation factor developed again.	Relationship factor assigned to developed distance factor, tool factor, anthropometry factor, and skill factor.	Metaheuristic Algorithm (Genetic Algorithm)	

3 Development of Conceptual Model

This conceptual model is developed based on model of Khorasanian et al. (2013). The initial model has function (1) and function (2).

$$DF_{ij} = \begin{cases} 1,0; & \text{if distance factor for } i \text{ and } j \text{ is "good"} \\ 0,5; & \text{if distance factor for } i \text{ and } j \text{ is "not good not bad"} \\ 0,1; & \text{if distance factor for } i \text{ and } j \text{ is "bad"} \end{cases} \quad (1)$$

$$TR_{ij} = a_1 DF_{ij} + a_2 TF_{ij}; \quad a_1 + a_2 = 1 \quad (2)$$

Then added some factor so it becomes :

DF_{ij} or TF_{ij} or MF_{ij} or LF_{ij} or SF_{ij}

$$= \begin{cases} 1,0; & \text{if distance factor for } i \text{ and } j \text{ is "good"} \\ 0,5; & \text{if distance factor for } i \text{ and } j \text{ is "not good not bad"} \\ 0,1; & \text{if distance factor for } i \text{ and } j \text{ is "bad"} \end{cases} \quad (3)$$

$$TR_{ij} = a_1 DF_{ij} + a_2 TF_{ij} + a_3 MF_{ij} + a_4 LF_{ij} + a_5 SF_{ij};$$

$$a_1 + a_2 + a_3 + a_4 + a_5 = 1 \quad (4)$$

Functions (3) and function (4) aims to provide an index of relationships according to the factors chosen and determined. Where DF_{ij} is a distance factor, TF_{ij} is a factor tool, MF_{ij} is a motion factor, LF_{ij} is a factor layout, SF_{ij} is a factor skill, and TR_{ij} is the relationship value of all factors.

$$ATC = 1 - \frac{\sum_{k=1}^{NS} \left(\left(\sum_{i=1}^{Nsk} \sum_{j=i+1}^{Nsk} TR_{\pi sk(i), \pi sk(j)} \right) / \left(\frac{Nsk}{5} \right) \right)}{NS} \quad (5)$$

Function (5) describes the ATC to provide a solution of the relationship of a predetermined factor. The next function aims to minimize number of stations, minimize number of mated-station, and minimize ATC.

$$S_R = [RTtotal/ct] \quad (6)$$

$$S_L = [LTtotal/ct] \quad (7)$$

$$S_E = \left[\max \left(\left(ETotal - ((S_L + S_R) \times ct - (LTotal + RTotal)) \right), 0 \right) / ct \right] \quad (8)$$

$$LB_{NS} = S_R + S_L + S_E \quad (9)$$

$$LB_{NM} = \max(S_L, S_R) + [\max((S_E - |S_L - S_R|), 0)/2] \tag{10}$$

Where RTtotal is the total processing time of the R type tasks, LTtotal is the total processing time of the L type tasks, and ETtotal is the total processing time of the E type tasks. ct represents cycle time and [x] denotes the smallest integer larger than or equal to x. LBNS is denote the lower bounds of the number of station and LBNM is the number of mated-station.

Using these lower bounds, the number of stations and the number of mated-stations criteria were transformed into $(NS - \frac{LBNS}{NS})$ and $(NM - \frac{LBNM}{NM})$ respectively. So, the objective function is defined by the following equation:

$$obj = w_1 \left(NS - \frac{LBNS}{NS} \right) + w_2 \left(NM - \frac{LBNM}{NM} \right) + w_3 ATC \tag{11}$$

Where $w_i, i = 1, 2, 3$, are the user-defined weights of the factors. The number of mated-stations may represent the line length. Also, the number of stations may denote the number of operators needed for the line. The effects of these two criteria on the efficiency of the line seem to be more than that of ATC. On the other hand, the number of stations is often considered more important than the number of mated-stations. Accordingly, $w_1 > w_2 > w_3$; $w_1 + w_2 + w_3 = 1$ should be satisfied.

Tables 2, 3, 4, 5, and 6 show the suggested values to be considered for each factor. The value has been tried to combine with all probability values so as to give a small ATC value. The smaller ATC values provide stronger factor relationships.

Table 2. Distance factor value.

Dfij	1	2	3	4
1	-	1,0	1,0	1,0
2		-	1,0	1,0
3			-	1,0
4				-

Table 4. Motion factor value.

Mfij	1	2	3	4
1	-	1,0	1,0	1,0
2		-	1,0	1,0
3			-	1,0
4				-

Table 6. Skill factor value.

Sfij	1	2	3	4
1	-	1,0	1,0	1,0
2		-	1,0	1,0
3			-	1,0
4				-

Table 3. Tool factor value.

Tfij	1	2	3	4
1	-	1,0	1,0	1,0
2		-	1,0	1,0
3			-	1,0
4				-

Table 5. Layout factor value.

Lfij	1	2	3	4
1	-	1,0	1,0	1,0
2		-	1,0	1,0
3			-	1,0
4				-

Table 7. Relationship value.

TRij	1	2	3	4
1	-	1,0	1,0	1,0
2		-	1,0	1,0
3			-	1,0
4				-

4 Conclusion and Future Work

The conclusion of the early stage in this research are valued factor and high proportion values can provide small relationship value so that additional factor is be effective in providing a solution for idle time reduction and minimize cycle time. Idle time and reduced cycle time can reduce the number of workstations so the work will be more effective.

Furthermore, the research will be applied to the observed object then compared the condition before the corrected with the suggestion of the value factor and after the improvement with the suggestion of given the value factor to know whether the modification of the model is right or not when applied to real condition.

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