









which have accessible control, can be controlled by buttons on screen. Technological flow chart is shown in figure 9.

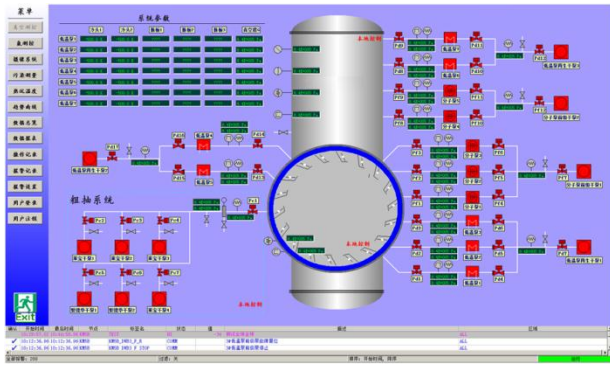


Figure 9. Technological flow chart

(2) Curve display: All the collected real-time data is displayed in the form of curve. Multiple curves can be displayed simultaneously or separately, and history curves can be queried. The schematic of curve display is shown in figure 10.

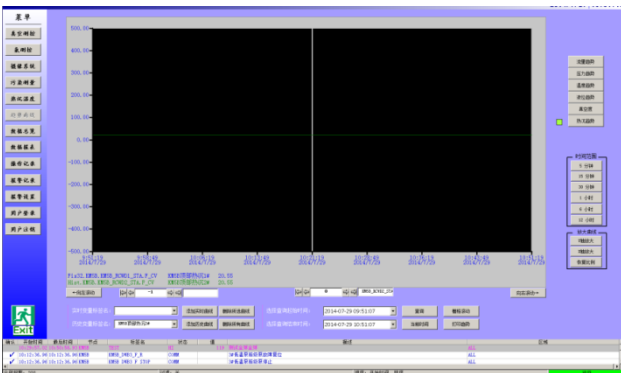


Figure 10. The schematic of curve display

(3) Date query: Establishing an independent data query can query the historical operating state and the historical date of the system, including operation logs and key historical date. The schematic of data query is shown in figure 11.

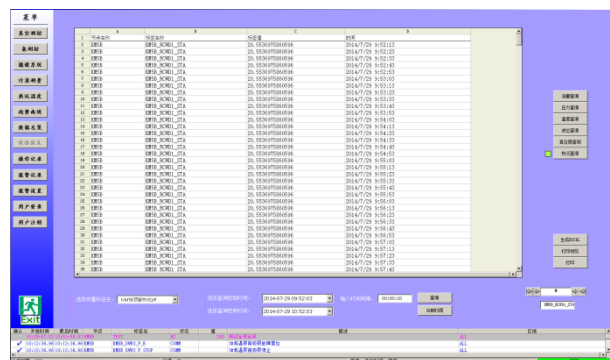


Figure 11. The schematic of data query

(4) Alarm information: Alarm information of the control system include the real-time alarm information

and historical alarm information. The current real-time alarm can be manually processed. The schematic of Alarm information is shown in figure 12.

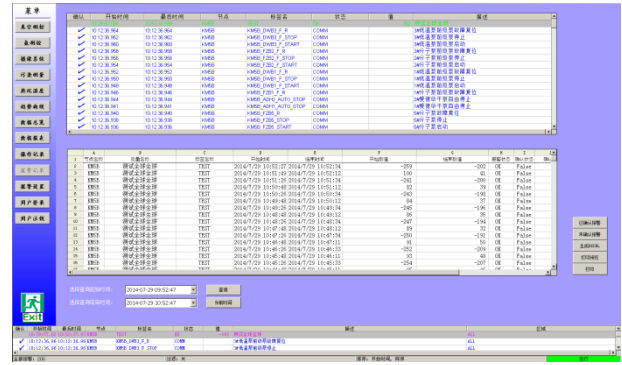


Figure 12. The schematic of alarm information

## 5 Conclusion

This paper introduces a large-scale near space plasma vacuum environment imitation technique. Through calculation and analysis, this paper provides a design scheme required for vacuum working environment. The negative pressure vessel system, vacuum subsystem, vacuum system is introduced in detail.

The finite element analysis and numerical calculation of the mechanical structure and the vacuum capacity verify the feasibility of the design. The indicators of the system proposed in this paper are qualified. It can effectively reduce the influence of wall effect in the research of space plasma.

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