

The New Information Grey Direct Model and Its Use in The Forecasting of Energy Constitutes

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Abstract. To overcome the contradiction of the traditional grey first order accumulate with the new information priority principle, this paper establish the new grey fractional order accumulate, which is proposed to better reflect the priority of the new information. Based on this, This paper establish the fractional order grey direct model based on the principle of new information priority, which is proposed to improve the prediction precision. The results of practical numerical examples demonstrate that this new method has a good predication performance for small data set forecasting. This research also provides a new model for the less data forecasting.

1 Introduction

Time series prediction refers to the process by which the future values of a system is forecasted based on the information obtained from the past and current data points [1]. GM(1,1) was first proposed by Deng [2-3], which is one of the most important parts in grey system theory, for small sample forecasting. Because the grey prediction model needs little origin data, has simple calculate process and higher forecasting accuracy, it has been successfully applied in many disciplines [4–7].

The purpose of GM (1, 1) model is to work on system forecasting with poor, incomplete or uncertain messages. However, the existing GM (1,1) model cannot be used for accurate prediction for many actual systems, while the system behaviors are affected more or less by other relative factors and their characteristic values never follow the Grey exponential law completely [8]. So, A large number of studies on improved Grey model and applications have been reported, such as Li et al. [9], Xie and Liu [10], Yang et al. [11]. Those improved Grey models all integrated traditional GM (1,1) model and other modeling technology, but not including the research on accumulated generating operator of Grey model.

Although grey forecasting model had been widely adopted, its predicting performance still could to be improved [9-15]. However, most of improved methods do not emphasize the value of new data, which has been put forward in the grey system by Deng, and named the new information priority principle. Dang and Luo improved GM (1,1) using the nth item of $X(0)(n)$ as the starting condition of the Grey differential model to increase prediction precision [12–15]. Because of the new data represents the future law of development of small sample system [2], we should considered more priority of the nth data than the n-1th data in the model. Similarly, the 2th data is more prior than the 1th data.

Recently, fractional order [16,17] has been applied on the grey generating function, which uses fractional order accumulative generation to narrow the variation of the sequential data and then establish the prediction model. Wu [16] established the grey system model based fractional order accumulative generation by applying the fractional order to grey model. In fact, GM (1,1) model only can simulate homogeneous index sequence, it will has large error when the original data is non-homogenous exponential sequence. So, the grey direct grey model has been formulated to non-homogenous exponential sequence [18,19]. This paper studies the grey direct grey model based on the technology of fractional order accumulation generation and the principle of priority of new information theory, we establish the optimized model and solve the optimization accumulation order value, then give it in practical application.

The rest of the paper proceeds as follows, the next section presents an overview of the relevant literature on grey model. The third section provides a new fractional order grey direct model with the principle of new information priority of grey system. The fourth section proves the advantage of the grey model put forward in this paper over the traditional grey model by one real case in China. Finally, the paper concludes with some comments in last Section.

2 Review on GM(1,1) model and grey direct model

2.1 GM(1,1) model [3]

Suppose that the non-negative sequence of raw data is $X(0)=(x(0)(1), x(0)(2), \dots, x(0)(n))$, and its sequence of the first-order accumulative generation operator on $X(0)$ is denoted as following,

$$X(1)=(x(1)(1), x(1)(2), \dots, x(1)(n)) \tag{1}$$

In formula (1),
$$x^{(1)}(k) = \sum_{i=1}^k x^{(0)}(i), \quad k=1,2,\dots,n$$

From the sequence $X(1)=(x(1)(1), x(1)(2), \dots, x(1)(n))$, we can derive the sequence of generated mean value of consecutive neighbors in the following, $Z(1)=(z(1)(2), \dots, z(1)(n))$; where

$$z(1)(k)=0.5 x(1)(k)+0.5x(1)(k-1), k=2, \dots, n.$$

Definition 1 For a non-negative sequence of raw data $X(0)$; $X(1)$ is a generated sequence with the application of the first-order accumulative generation operator on $X(0)$; $Z(1)$ is a sequence with the application of the generated mean value of consecutive neighbors operator on $X(1)$, then the following equation

$$x(0)(k)+a z(1)(k)=b, k=2, \dots, n. \tag{2}$$

is a grey differential equation, also called model GM(1,1).

And the equation

$$\frac{dx^{(1)}}{dt} + ax^{(1)} = b \tag{3}$$

is the whitened equation of GM(1,1). If we let

$$Y = \begin{bmatrix} x^{(0)}(2) \\ x^{(0)}(3) \\ \vdots \\ x^{(0)}(n) \end{bmatrix}, \quad B = \begin{bmatrix} -z^{(1)}(2) & 1 \\ -z^{(1)}(3) & 1 \\ \vdots & \vdots \\ -z^{(1)}(n) & 1 \end{bmatrix}$$

One can use formula (2) to make a least square estimation for parameters $\hat{a} = [a, b]^T$,

$$\hat{a} = (B^T B)^{-1} B^T Y \tag{4}$$

After obtaining parameters a and b , use formula (5) to define time response formula and use formula (6) to define reducing value sequence.

$$\hat{x}^{(1)}(k+1) = (x^{(0)}(1) - \frac{b}{a})e^{-ak} + \frac{b}{a}, \quad k=1,2,\dots,n-1 \tag{5}$$

$$\hat{x}^{(0)}(k+1) = (1 - e^a)(x^{(0)}(1) - \frac{b}{a})e^{-ak}, \quad k=1,2,\dots,n-1 \tag{6}$$

Finally, one should make error test. The residual sum of squares is shown as formula (7).

$$s = \varepsilon^T \varepsilon = \sum_{k=1}^m (x^{(0)}(k) - \hat{x}^{(0)}(k))^2 \tag{7}$$

Professor Deng points out that the whitened equation and its corresponding time response function cannot be derived from the GM(1,1) directly, which are some approximate replacement.

2.2 Grey direct model [18-20]

Definition 2 Assume that a non-negative sequence $X(0)=(x(0)(1), x(0)(2), \dots, x(0)(n))$ is given, then

$$\hat{x}^{(0)}(k+1) = \beta_0 + \beta_1 \hat{x}^{(0)}(k) \tag{8}$$

is referred to as the original form of the auto-regressive GM(1,1) model (ARGM(1,1)), or grey direct model.

Theorem 1 Assumed that $X^{(0)}$ is defined by the Definition 2,

$$B = \begin{bmatrix} 1 & x^{(0)}(1) \\ 1 & x^{(0)}(2) \\ \vdots & \vdots \\ 1 & x^{(0)}(n-1) \end{bmatrix}, \quad Y = \begin{bmatrix} x^{(0)}(2) \\ x^{(0)}(3) \\ \vdots \\ x^{(0)}(n) \end{bmatrix}$$

Then the least squares estimation values are

$$\hat{\beta} = (B^T B)^{-1} B^T Y$$

Among that $\hat{\beta} = (\beta_0, \beta_1)^T$ is the parameters list of the formula (8).

Theorem 2 Assume that B 、 Y and $\hat{\beta}$ are defined by the Theorem 1, and let $\hat{x}^{(0)}(1) = x^{(0)}(1)$, then

$$\hat{x}^{(0)}(k+1) = [x^{(0)}(1) - \frac{\beta_0}{1-\beta_1}] \beta_1^k + \frac{\beta_0}{1-\beta_1} \tag{9}$$

Literature [18] pointed out that if the original data is monotonous movements bump geometry, then the application of the formula (8) as shown in the simulation data obtained with the same sequence of model geometry; moreover formula (8) model can fully simulate inhomogeneous index sequence.

Because grey auto-regressive method of GM(1,1) is formulated by using the original data rather than the accumulated generation data, it does not need to inverse accumulated generating. We can see that formula (6) is an exponential model, formula (9) is a non-homogenous exponential model.

3 Fractional order grey direct model with the new information priority

3.1 Fractional order accumulate with the new information priority

Fractional contains an "in between" thinking, more and more scholars recognized [16,22], The recent studies have shown that we can enhance the accuracy of gray forecast modeling by select the appropriate fractional order [16].

Definition 3 [16]. Assume that $r=q/p$ and $\{x_j : j=1, \dots, m\}$ which is a nonnegative sequence, are given, then

$$\sum_{j=1}^m {}^{(r)}x_j = \sum_{j=1}^m C_{m-j+r-1}^{m-j} x_j \tag{10}$$

is called the r order accumulated, and define

$$C_{r-1}^0 = 1, C_{m-j+r-1}^{m-j} = \frac{(m-j+r-1)(m-j+r-2) \cdots (r+1)r}{(m-j)!}$$

Supposed that $X^{(0)}=(x^{(0)}(1), x^{(0)}(2), \dots, x^{(0)}(n))$ is non-negative sequence, application of gray system accumulate, we can get the r order accumulated generating sequence $X^{(r)}$ of $X^{(0)}$ is $X^{(r)}=(x^{(r)}(1), x^{(r)}(2), \dots, x^{(r)}(n))$, where $x^{(r)}(k) = \sum_{j=1}^k C_{k-j+r-1}^{k-j} x^{(0)}(j)$, $k=1, \dots, n$. Since $X^{(0)}$ is time series data, the acquired time from $x^{(0)}(1)$ to $x^{(0)}(n)$ is decreasing by the view of time, that is to say, $x^{(0)}(1)$ is the earliest data and $x^{(0)}(n)$ is the latest data, so, $x^{(0)}(1)$ may be referred to as the oldest information and $x^{(0)}(n)$ for the newest message.

From the above r order accumulated generating function, we can see that every accumulate contains the oldest data $x^{(0)}(1)$, that is, we have used the oldest data n times, and as the latest information $x^{(0)}(n)$, is only used once in the $x^{(r)}(n)$ calculation, which is obviously contradicts with the principle of new information priority in grey system theory. In fact, $x^{(0)}(n)$, as the latest information, is the latest incarnation of the historical, and can be better reflect the internal development and trends of the system. The principle of new information priority is the key point of view about information applied in grey systems theory. That is, by applying additional weights on newer information, one can achieve a better effect from grey prediction. Therefore, the latest information should be paying more consideration when we establish the model and get model parameters. Based on this, we will provide a new cumulative method which can reflect the new information's effect in the following.

Definition 4 For $r=q/p$ and non-negative sequence $X(0)=(x(0)(1), x(0)(2), \dots, x(0)(n))$, then, the r order cumulative $X(r)=(x(r)(1), x(r)(2), \dots, x(r)(n))$ is called the fractional accumulated generating with the new information

$$x^{(r)}(k) = \sum_{j=k}^n C_{n-j+r-1}^{n-j} x^{(0)}(j)$$

priority where

Fractional derivatives accumulate the whole history of the system in weighted form. The larger r of $x(r)(k)$ is, the larger the weight of old data is; the smaller r of $x(r)(k)$ is, the smaller the weight of old data is. Reducing r can reduce the weights of old data, which can put more emphasis on the newer data.

But from the definition 4, for any k , we can see that all new data have been contained in the $x^{(r)}(k)$, and the more new data, the more weight has been putted because of $C_{n-j+r-1}^{n-j}$ is accessioned with j 's increases. So, the text of the accumulated sequence obtained this way is called the accumulation of new information accumulated priority sequence.

3.2 Fractional order grey direct model with the new information priority

Definition 5 Assume that a non-negative sequence $X^{(0)}=(x^{(0)}(1), x^{(0)}(2), \dots, x^{(0)}(n))$ is given, then

$$\hat{x}_{(0)}^{(r)}(k+1) = \beta_0 \sum_{j=k}^{n-1} C_{n-1-j+r-1}^{n-1-j} + \beta_1 \hat{x}_{(0)}^{(r)}(k) \tag{11}$$

is called r order grey direct model based on the new information priority, where

$$x_{(0)}^{(r)}(k) = \sum_{j=k}^n C_{n-j+r-1}^{n-j} x^{(0)}(j), \quad k = 1, 2, \dots, n-1.$$

Formula (11) and formula (8) is the same in the form, in fact, they are different to each other, the difference lies in the way of data generated essentially. The innate character difference makes the new grey model can not only reflect the new information priority principle of gray system, but also has better accuracy than old, and the advantages of the new model will present in the example. In addition, if $r=1$, the new model reduces to the literature [20] given model, that is the model of formula (11) shown in more general.

Theorem 3 Assumed that $X^{(0)}$ and $\hat{x}_{(0)}^{(r)}(k)$ are defined by the Definition 5,

$$B = \begin{bmatrix} \sum_{j=1}^{n-1} C_{n-1-j+r-1}^{n-1-j} & \sum_{i=1}^n C_{n-i+r-1}^{n-i} x^{(0)}(i) \\ \sum_{j=2}^{n-1} C_{n-1-j+r-1}^{n-1-j} & \sum_{i=2}^n C_{n-i+r-1}^{n-i} x^{(0)}(i) \\ \vdots & \vdots \\ \sum_{j=n-1}^{n-1} C_{n-1-j+r-1}^{n-1-j} & \sum_{i=n-1}^n C_{n-i+r-1}^{n-i} x^{(0)}(i) \end{bmatrix}, \quad Y = \begin{bmatrix} \sum_{i=2}^n C_{n-i+r-1}^{n-i} x^{(0)}(i) \\ \sum_{i=3}^n C_{n-i+r-1}^{n-i} x^{(0)}(i) \\ \vdots \\ \sum_{i=n}^n C_{n-i+r-1}^{n-i} x^{(0)}(i) \end{bmatrix}$$

Then the least squares estimation values are

$$\hat{\beta} = (B^T B)^{-1} B^T Y \tag{12}$$

Among that $\hat{\beta} = (\beta_0, \beta_1)^T$ is the parameters lists of the formula (11).

Theorem 4 Assume that a non-negative sequence $X^{(0)} = (x^{(0)}(1), x^{(0)}(2), \dots, x^{(0)}(n))$ is given. Actually, Let error is u ; then

$$x^{(0)}(k+1) = \beta_0 + \beta_1 x^{(0)}(k) + u_k, \quad k=1, \dots, n-1 \tag{13}$$

Via the treatment of new information priority, the mean of the error is $E(Au)$:

$$E(Au) = u_n + \frac{(n-2)C_{n-(n-1)+r-1}^{n-(n-1)}}{n-1} u_{n-1} + \dots + \frac{2C_{n-3+r-1}^{n-3}}{n-1} u_3 + \frac{C_{n-2+r-1}^{n-2}}{n-1} u_2;$$

Where

$$A = \begin{bmatrix} C_{n-2+r-1}^{n-2} & C_{n-3+r-1}^{n-3} & \dots & C_{n-(n-1)+r-1}^{n-(n-1)} & C_{n-n+r-1}^{n-n} \\ 0 & C_{n-3+r-1}^{n-3} & \dots & C_{n-(n-1)+r-1}^{n-(n-1)} & C_{n-n+r-1}^{n-n} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & \dots & 0 & C_{n-(n-1)+r-1}^{n-(n-1)} & C_{n-n+r-1}^{n-n} \\ 0 & \dots & 0 & 0 & C_{n-n+r-1}^{n-n} \end{bmatrix}, \quad u = \begin{bmatrix} u_1 \\ \vdots \\ u_{n-2} \\ u_{n-1} \end{bmatrix}$$

Proof: Let

$$Y_1 = \begin{bmatrix} x^{(0)}(2) \\ \vdots \\ x^{(0)}(n-1) \\ x^{(0)}(n) \end{bmatrix}, \quad B_1 = \begin{bmatrix} 1 & x^{(0)}(1) \\ \vdots & \vdots \\ 1 & x^{(0)}(n-2) \\ 1 & x^{(0)}(n-1) \end{bmatrix}$$

Then via the treatment of new information priority, formula (13) becomes

$$AY = AB \begin{bmatrix} \beta_0 \\ \beta_1 \end{bmatrix} + A\mu$$

Obviously $E(Au) = u_n + \frac{(n-2)C_{n-(n-1)+r-1}^{n-(n-1)}}{n-1} u_{n-2} + \dots + \frac{2C_{n-3+r-1}^{n-3}}{n-1} u_2 + \frac{C_{n-2+r-1}^{n-2}}{n-1} u_1$ Because of

$$C_{n-i+r-1}^{n-i} = \frac{(n-i+r-1)(n-i+r-2)\dots(r+1)r}{(n-i)!} \leq 1$$

So,

$$E(Au) = u_{n-1} + \frac{(n-2)C_{n-(n-1)r-1}^{n-(n-1)}}{n-1}u_{n-2} + \dots + \frac{2C_{n-3+r-1}^{n-3}}{n-1}u_2 + \frac{C_{n-2+r-1}^{n-2}}{n-1}u_1$$

$$\leq u_{n-1} + \frac{n-2}{n-1}u_{n-2} + \dots + \frac{2}{n-1}u_2 + \frac{1}{n-1}u_1$$

That is the average error of the simulation sequence is more small when we consider the fractional order accumulate with the new information priority.

4 The determine to the fractional order parameter of grey direct model based on the new information priority

Based on the discussion above, we can see that the fractional cumulative model’s average error is smaller, so the new model has better modeling accuracy. Of course, how to choose the accumulated order r is an important issue. A simple and natural way is establish an optimal model to get the cumulative order r , such as the average relative error of simulation data sequence to establish minimum target on the cumulative order optimization model. Therefore, we will establish the cumulative order optimization model, the goal is minimization the simulate sequence’s average relative percentage error (*ARPE*).

$$\min ARPE$$

$$s.t \quad ARPE = \frac{1}{n-1} \sum_{k=1}^{n-1} |\hat{x}^{(0)}(k+1) - x^{(0)}(k+1)| \quad (14)$$

$$\hat{x}^{(0)}(k+1) = [x^{(0)}(1) - \frac{\beta_0}{1-\beta_1}] \beta_1^k + \frac{\beta_0}{1-\beta_1}$$

$$r > 0$$

Obviously, the above optimization model (14) is a nonlinear optimization model; we will use the modern intelligent algorithms, such as genetic algorithms, simulated annealing algorithm, PSO et.al, to solve this model. So, in the next computational analysis, we will use the PSO algorithm to get the accumulated order r .

PSO(Particle Swarm ,PSO) is a kind bionic optimization algorithm, and the method comes from the simulation of motor behaviour of birds and fish [21].Assumed the objective is a n dimensional function, the size of particle population is m , the i -th particle’s “best” value is p_i^{best} , and global “best” value is p_g^{best} , then the i -th particle modified its velocity and position according to the following formulas:

$$\begin{cases} v_{id} = w \cdot v_{id} + c_1 \text{rand}() (p_{id}^{best} - x_{id}) + c_2 \text{Rand}() (p_g^{best} - x_{id}) \\ x_{id} = x_{id} + v_{id} \end{cases}$$

Where $i=1, \dots, m$, $d=1, \dots, n$, $\text{rand}()$ and $\text{Rand}()$ are two separately random function in the range $[0,1]$, c_1 and c_2 are constants known as acceleration coefficients and $c_1=c_2=2$, w is the weigh value of the inertia.

Algorithm process of particle swarm optimization:

Step1: Initializing the population size of particles , every particle’s velocity and position;

Step2: For every particle, according to the formula(3) to calculate $\hat{\beta} = (\beta_0, \beta_1)^T$, then according to the formula (4), $\hat{x}^{(0)}(k+1)$, $k=1,2, \dots, n-1$ are obtained;

Step3: Calculating every particle’s fitness value and get p_i^{best} and p_g^{best} ;

Step4: Updating each particle’s velocity v_i and position x_i according to the formula(6) ;

Step5: if the stop condition (the iteration number or the error precision satisfy the request) is satisfied, the iteration stop and output the p_g^{best} , that is the optimization r ; otherwise turn to step 2.

5 Example:the simulation of natural gas consumption in china

Energy has an influencing role in achieving economic and social progress. Forecasting energy Constitutes a vital part of energy policy of a country, especially for a developing country like China whose economy is in a stage of energy transition: from low efficiency solid fuels to oil, gas and electric power. A large number of studies on energy consumption forecasting using grey model and improved grey model have been reported, such as Wu et al [20] , Xu et al [23], Li et al [24].

In this section, the advantage of the fractional order grey direct model based on the new information priority over the other grey models is demonstrated by natural gas consumption in china. Average relative percentage error (*ARPE*) compares the real and forecasted values to evaluate the precision.

We consider an example from paper [23] which provides the sample data. Using the data from 1995 to 2006 (in-sample data) to construct fractional order grey direct model based on the new information priority:

$$x(k) = 24.2617 \times 1.268^k + 141.6864 \quad (15)$$

then predict the actual value from 2007 to 2008.

Actual values and the forecasting values of three compared models are presented in Table 1. As can be seen from Table 1, fractional order grey direct model based on the new information priority yielded the lowest *ARPE* compared with the other models across all the period from 1995-2008, which also illustrate that the new model is more suitable for natural gas consumption.

Table 1. The fitted values and ARPE of four grey models.

Year	Natural gas consumption (From China government webpage)			
	Actual value	model (15)	GMNI(1,1) [20]	reference [23]
1995	177.531	172.406	173.677	190.243
1996	188.049	180.655	181.593	183.658
1997	176.132	191.119	191.694	184.908
1998	218.699	204.395	204.583	193.994
1999	215.337	221.231	221.030	210.914
2000	244.811	242.592	242.015	235.669
2001	274.554	269.687	268.793	268.259
2002	292.180	303.058	302.961	308.685
2003	339.454	347.569	346.559	356.945
2004	397.285	402.968	402.191	413.040
2005	486.936	474.128	473.177	476.970
2006	561.051	562.129	563.756	548.735
ARPE (%)	-	3.12	3.092	4.406
2007	698.903	675.029	679.333	721.62
2008	807.857	818.246	826.811	925.69
ARPE (%)	-	2.35	2.573	10.75

6 Conclusion

Based on principle of priority of new information in the grey system theory, this paper establish a new information accumulates method by use of Fractional accumulate ideas; based on this, a new fractional order direct gray model with information priority has been presented, and given the model parameters with least squares estimation; and analyzed the simulation error of the new model. The results show that fractional order gray direct model with the new information priority can reduce simulation error; the application example also show that the new model has better prediction accuracy and prediction accuracy of analog data. Although the proposed model overcomes the defects of parameters estimation in traditional direct grey model, they may be superior to other modeling methods in some aspects. There are some potential drawbacks such as the selection of tradeoff parameter related to a least squares cost function. The performance of this model is more related to the selection of trade-off parameter. Thus, how to quickly and accurately select the model trade-off parameter should be further studied. Further, by calculating, we have found that the prediction error maybe worse when we use the accumulated order, which can be obtained by the minimize averaging the error between the raw data and simulation data. Therefore, in order to get the optimization cumulative order, what evaluation criteria as objective function is suitable is also an important issue for future research process.

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