Study on the Curvature Reducing Method of Non-linear Regression Model

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Abstract. The method to reduce the non-linear strength (curvature) of non-linear regression model was studied in this paper. Firstly, the reference point of the non-linear strength was analyzed. Based on the definition of curvature cubic matrix, a computing method of curvature cubic matrix was proposed based on the Cholesky disassembling. Then the common ways to reduce the non-linear strength was also discussed. Pointed at some common non-linear models in real engineering applications, such as non-linear models used for multiple-measurement and mutual-calibration of different instruments, or non-linear models with prior information, a new least square method with weight was given, which can evidently reduce the curvature of these multi-structure non-linear regression models, therefore evidently reduce the non-linear strength. Finally, the Numerical simulation results were given to validate the effectiveness and feasibility of this weighted least square method. The method to reduce the non-linear strength (curvature) of non-linear regression model was studied in this paper. Firstly, the reference point of the non-linear strength was analyzed. Based on the definition of curvature cubic matrix, a computing method of curvature cubic matrix was proposed based on the Cholesky disassembling. Then the common ways to reduce the non-linear strength was also discussed. Pointed at some common non-linear models in real engineering applications, such as non-linear models used for multiple-measurement and mutual-calibration of different instruments, or non-linear models with prior information, a new least square method with weight was given, which can evidently reduce the curvature of these multi-structure non-linear regression models, therefore evidently reduce the non-linear strength. Finally, the Numerical simulation results were given to validate the effectiveness and feasibility of this weighted least square method.

Keywords: Non-linear regression, curvature, cholesky disassembling, least square with weight.

Introduction

Because of the complexity of non-linear function, currently the parameter estimate of non-linear regression mainly solved by linear approximating. The precision of the estimate
result rests with the approximate level with linear model. That is the. Beale put forward the measurement of non-linear strength firstly in [1]. Bates and Watts defined inherent curvature and parameter effect curvature in 1980[2]. Their definition applied successfully. Document [3] put forward the concept of curvature cubic matrix. We are investigating how to reduce curvature of non-linear model.

Definition

Non-linear regression usually can be expressed as $Y = f(X, \beta) + \epsilon$, in which measurement data $Y = (y_1, y_2, L, y_n)^T$, unknown parameter $\beta = (\beta_1, L, \beta_p)^T$, $f(X, \beta)$ is the non-linear function with design matrix $X$ and unknown parameter $\beta$. Measurement error $\epsilon = (\epsilon_1, \epsilon_2, L, \epsilon_n)^T$ obeys $\epsilon \sim (0, \sigma^2I_{n\times n})$. The definition is as follows: The inherent curvature and parameter effect curvature cubic matrixes of non-linear model $Y = f(X, \beta) + \epsilon$ are

\[
I_{(n-p)\times(n-p)} = \left[ N_x^{\epsilon} \right] \left[ U_{nxp} \right],
\]

\[
P_{pxp} = \left[ Q_p^{\epsilon} \right] \left[ U_{nxp} \right],
\]

\[
Y_{jg} = \sum_{i=1}^n A_{gi} X_{ij} , Y_{mpq} = [A_{mnp}] [X_{n Duch}],
\]

The QR disassembling of Matrix $V$ is the most important step. We can get form Cholesky disassembling theory that if $G = (g_{ji})_{pxp}$,

\[
G = LDL', as a result that
\]

\[
d_j = g_{jj} - \sum_{r=1}^{j-1} c_{jr}^2 d_r^{-1},
\]

\[
c_{ij} = g_{ij} - \sum_{r=1}^{j-1} c_{ir} c_{jr} d_r^{-1}, (j = 1, L, p, i = j + 1, L, p),
\]

\[
l_{ij} = \frac{c_{ij}}{d_j}.
\]

From this easily get L and D. Because $V$ is symmetry positive definite matrix, disassembling it as Cholesky disassembling theory, $V^{\epsilon} = LDL' = (L\sqrt{D})(\sqrt{D})^T$ , given $R = (L\sqrt{D})^T$, $Q = V[(L\sqrt{D})^T]^T$ ,that is QR disassembling of $V$.Curvature cubic matrix is the standard of non-linear strength. An important direction is reducing the non-linear strength of the model or reducing the curvature. Sum up the methods of reducing the curvature. We get three methods, Parameter varying, increasing sampling, least square method with weight. Document [3] pointed out that inherent curvature is the inherent characteristic of the model. It will remain unchanged if parameter varies. Parameter effect curvature relies parameter. In practice, different parameter varying should be chose suitably according to concrete problem at different models. Because parameter varying has not simple and explicit calculation method, many learned man tried different ways to reduce curvature. Document [4] put forward the method of increasing sampling and proofed that if provided enough
sampling data, the non-linear model can approach the linear model adequately. In practice, the prior information $\forall \hat{\beta} \in \Theta$ can be defined and then model curvature will be reduced on ceasing sampling. When the non-linear model approaches linear model adequately, the least square iteration method can be used to calculate $\hat{\beta}$.

$$Y(\rho) = F_{\rho}(X, \beta) + \varepsilon(\rho), \varepsilon(\rho) = \begin{pmatrix} 0, \text{diag}(\rho_1 \sigma_1^2, \ldots, \rho_n \sigma_n^2) \end{pmatrix}.$$  \hspace{1cm} (3)

The discussion about the existence and superiority of the optimal weighting can be referred to document [5].

**Example**

Grow model is the most widely applied model in agriculture, biological, economy, chemical. The harvest of the crops $y$ increases with $x$, but suffered from environment and weather, so we built Gompertz model: $Y_i = \exp(\beta_1 - \beta_2 \beta_3^x) + \varepsilon_i$, in which $\beta_i$ are the influencing factor we should think about. Because there are function relation between harvest and density of crops, so we can build another Holliday model. $Y_2 = (\beta_1 + \beta_2 + \beta_3 x^2)^{-1} + \varepsilon_2$. Unite the two models. We can get the non-linear multi-structure model. Set up $\varepsilon_1 \sim N(0,0.01^2), \varepsilon_2 \sim N(0,0.01^2)$, $\beta = (\beta_1, \beta_2, \beta_3)' = (8,1,2)'$, $x = 1, 2, \ldots, 100$, and might as well $z = 1, 2, \ldots, 100$.

Simulation the measurement data $\{Y_{1i}\}_{i=1}^{100}$ and $\{Y_{2i}\}_{i=1}^{100}$. We simulated 50 times and then statistic the data. Lead weight into model. Set up weights $\rho_1 = \rho, \rho_2 = 1 - \rho$, iteration initial value $(8.5, 1.5, 1.7)$ and step length 0.1. Iterate with G-N formula. The computing result is as follows.

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### Conclusion

The curvature of Gompertz model is larger than the one of Holliday model. The curvature of Holliday model is very small. It explains that the Holliday model is close to linear model. The estimate result also displayed that Holliday model is more accurate than Gompertz model. The curvature of multi structure is nearly zero. It shows that multi-structure model can use all information fully to get precise least-square estimate. The method with optimal weight can get litter curvature than traditional treatment. The least square with weight can get more precise result.

### References


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