DC-link Voltage Control to Compensate Voltage Deviation for PV–BESSs Integrated System in Low-Voltage (LV) Networks

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Abstract. The exhaustion of fossil fuel and the greenhouse gas emission are one of the most significant energy and environmental issues, respectively. Photovoltaic (PV) generators and battery energy storage systems (BESSs) have been significantly increased for recent years. The BESSs are mainly used for smoothing active power fluctuation of the PV. In this paper, PV–BESSs integration of two DC/DC converters and one AC/DC converter is investigated and DC-link voltage control to compensate the AC voltage deviation is proposed for the PV–BESS system in low-voltage (LV) networks.

1 Introduction

The exhaustion of fossil fuel and environmental pollution have made high interest toward renewable energies. Therefore, researches on grid-connected photovoltaic (PV) systems have been significantly increased. The PV systems can be adopted in both low-voltage (LV) systems and higher voltage system. Numerous researches on the PV systems have been studied, especially on integrating PV–energy storage system (ESS) have been increased in recent years. Since the active power fluctuation of the PV system may make the system unstable, the ESSs are mainly used with the PV systems to prevent the system from instability. For instance, providing an average power reference to the PV system may help the stable operation of the PV–ESS integrated system in the perspective of smoothing active power.

Two types of the PV–ESS integrated systems shown in Figure 1 are investigated in this paper. An AC integrating system, depicted in Figure 1(a), uses two AC/DC converters on smoothing PV fluctuation. On the other hand, a DC integrating system, depicted in Figure 1(b), uses one AC/DC converter. In the DC integrating system, two DC/DC converters should be installed for voltage stability of a common DC bus. Control strategies of the DC/DC converters and operation scheme of PV–ESS systems were proposed in [1–6]. High-gain DC/DC converters and control strategies for large-scale PV systems were proposed in [1]. Basic operation scheme of the PV-ESS system with DC integration was investigated in [2]. However, existing method didn’t consider an abnormal condition of BESS and only used the BESS output for smoothing.

Unlike general high or medium voltage system, X/R ratios of LV systems are under 0.5. Because a resistive component is much bigger than an inductive component, voltage fluctuation is highly dependent on active power fluctuation. Therefore the high penetration of intermittent renewable energy sources (RESs) in the LV networks may cause voltage instability. Various types of voltage control methods in the LV networks were investigated and proposed in [7–10]. The voltage–active power (∆V–P) droop control method was proposed and basic formulations of active and reactive power in the LV network were investigated in [7]. Relationships between voltage and active power proposed in above papers are used for proposed method. Characteristics of the LV systems are investigated in [8–9].

By smoothing active power fluctuation of PV using ESS, battery state-of-charge (SOC) should be undesirably deviated from the scheduled value. However the deviation may make the SOC value exceed the limit. An excess of the SOC limit causes under-voltage or over-voltage in the steady-state. Other papers didn’t consider how SOC limit affects to stability of systems. In this paper, the system voltage compensation method is proposed to mitigate voltage deviation. The proposed method was applied to the PV–ESS integrated system and tested by MATLAB/SimPowerSystems to prove its effectiveness.

Figure 1. Two types of PV–ESS integration method
2 Modeling

2.1 Battery Energy Storage System (BESS)

The BESSs are composed of DC voltage ans state-of-charge (SOC). A simple battery model has proportional DC voltage to SOC. DC voltage deviation from the SOC is not considered in this paper. SOC is simply regarded as energy remaining of battery. SOC at time $t_0+\Delta t$ is modeled as equation (1).

\[
SOC_{t_0+\Delta t} = SOC_t - \int_{t_0}^{t_0+\Delta t} \frac{I_c}{Q_c} dt
\]

where, $Q_c$ is capacity of the battery.

2.2 DC/DC Converter

There are two types of DC/DC converters in DC integrated systems. One is the DC/DC converter used in connecting the PV and a common DC bus. The other is the converter used in connecting the BESSs and the common DC bus. Current of the DC/DC converter used in the PV integrating is always positive so buck-boost converter topology is used. On the other hand, bi-directional buck-boost converter topology is used in integrating the BESSs and the common DC bus. Figure 2 is the one-way buck-boost topology and Figure 3 is the bi-directional buck-boost converter topology which are used in the PV-ESS integrated systems.

![Figure 2. Simple buck-boost converter topology](image)

![Figure 3. Bi-directional buck-boost converter topology](image)

Both two converters have gains from 0 to inf. ideally. The DC/DC converter connected to the PV operates at maximum power point tracking (MPPT) control scheme. For using actual measurement data of the PV power, assuming the MPPT control is successfully conducted is valid. So the PV-connected DC/DC converter is operated by power referenced control scheme. The control scheme of the buck-boost converter is shown in Figure 4.

In the PV–BESSs integrated systems, output power of BESSs is a difference between the PV average power and the actual power. The PV average power can be calculated in many ways. The BESSs-connected DC/DC converter is also operated by power referenced control scheme and the power reference is calculated from the actual PV output power and the average output power. The control scheme of bi-directional converter is shown in Figure 5.

![Figure 4. The control scheme of simple buck-boost converter](image)

![Figure 5. The control scheme of bi-directional converter](image)

2.3 AC/DC Converter

Half-bridge 2-level voltage sourced converter (VSC) is used in the PV–ESS integrated systems. DC voltage of the common DC bus should be maintained constant. Therefore $V_{dc-Q}$ control scheme is used in the AC/DC converter. The control scheme is shown in Figure 6.

![Figure 6. The control scheme of AC/DC converter](image)

3 DC Voltage Compensation Method

3.1 Formulation

We can define a duty ratio (D) of the AC/DC converter which means time ratio positive voltage is applied at AC systems. Using the duty ratio, relation between $V_{dc}$ and magnitude of equivalent AC voltage ($|V_{ac}|$) is shown in equation (2).

\[
|V_{ac}| = D(\frac{V_{dc}}{2}) + (1-D)(-\frac{V_{dc}}{2}) = (D-1/2)V_{dc}
\]

Equation (2) implies that steady-state AC voltage magnitude is proportional to DC voltage and the duty ratio. By using a Pulse Width Modulation (PWM), D should be changed continuously. On the other hand, DC voltage reference can be changed instantaneously.
3.2 SOC Limit

General the BESSs control scheme contains ON/OFF selector based on the SOC level. If the BESSs are on charging state, the SOC is increasing proportional to DC current. Otherwise, the SOC is decreasing. At \( SOC_{\text{min}} < SOC < SOC_{\text{max}} \), the BESSs can operate in both charging and discharging state. If the \( SOC = SOC_{\text{max}} \), BESSs cannot operate in discharging state. And BESSs cannot operate in charging state at the \( SOC = SOC_{\text{min}} \).

This ON/OFF selector can make sudden output power decrease or increase because the SOC limit changes the BESSs operate mode instantaneously. This discontinuity makes output decrease or increase in steady-state. If the connected AC grid is the low-voltage (LV) system, sudden output deviation may cause voltage instability. DC-link voltage control scheme to compensate voltage deviation is proposed to relax the voltage instability.

3.3 DC-link Voltage Control for Compensation

Sudden BESS off-signal due to SOC minimum value make voltage drop of AC bus. If the BESS control block operates on discharging state for a long time, under-voltage condition lasts for a long time. Sudden increase of DC voltage reference value can relax the under-voltage condition because \( |V_{\text{ac}}| \) is proportional to \( V_{\text{dc}} \). Over-voltage condition is also be relaxed by \( V_{\text{dc}} \) compensation.

![Figure 7. DC-link voltage control block](image)

DC-link voltage control block to compensate voltage deviation is shown in Figure 7. Because compensation method can cause bad effect to smoothing the PV output, compensation gain should be adjusted to appropriate value [7]. This control scheme can be applied at low-voltage system. In the next section, we validate proposed method using simulation.

4 Simulation

This section presents simulation results of the PV-BESS DC integrated module and proposed method. MATLAB/SimPowerSystems simulation tools are used in validation. Table 1 is the parameters used for the proposed PV system.

<table>
<thead>
<tr>
<th>Table 1. The parameter used for simulation</th>
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<tbody>
<tr>
<td>PV Module</td>
</tr>
<tr>
<td>DC Voltage (Vdc)</td>
</tr>
<tr>
<td>Maximum Output</td>
</tr>
<tr>
<td>BESS Module</td>
</tr>
<tr>
<td>DC Voltage (Vdc)</td>
</tr>
<tr>
<td>Maximum Output</td>
</tr>
<tr>
<td>Capacity (Q)</td>
</tr>
<tr>
<td>DC/DC Converter (Bi-directional)</td>
</tr>
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<td>Switching Frequency</td>
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<td>Input Inductor</td>
</tr>
<tr>
<td>Output Inductor</td>
</tr>
<tr>
<td>Capacitor</td>
</tr>
<tr>
<td>Other Parameter</td>
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<td>DC Bus Voltage</td>
</tr>
<tr>
<td>Grid Voltage (Line-to-Line)</td>
</tr>
<tr>
<td>Grid Frequency</td>
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<tr>
<td>X/R Ratio</td>
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For validation of SOC minimum limit, we assume that output of BESS is always positive in the simulation. Also sum of DC current references of PV and BESS is constant. In the simulation, the value is 2.5 (pu). PV data is actual measurement data of Hokkaido, Japan. We use the data with time scaling because actual fluctuation is less severe than expected one. SOC minimum limit is 0.2. Figure 8 is simulation results of under-voltage situation without DC voltage compensation. Figure 9 is simulation results of under-voltage situation with DC voltage compensation. Table 2 shows steady-state AC voltage before and after BESS is off.

![Figure 8 and Figure 9. Simulation results](image)
The SOC of BESSs reaches to its minimum value at time 1.17 sec. Because of limitation, sudden decrease of the PV-BESSs integrated system occurs. Figure 8(d) and figure 9(a), DC voltage is always constant if voltage deviation occurs. In figure 9(b), DC voltage is increase because of the proposed compensation scheme. Voltage compensation scheme is validate in the simulation and proposed method can be novel and adequate method in voltage deviation.

5 Conclusion

The disadvantage of PV systems is their unstable power output. This unstable output can cause voltage instability in the LV systems. The BESSs are used for preventing the instability. However, BESSs have SOC limit in operation. If BESSs’ SOC reaches its maximum or minimum value, sudden voltage deviation can occur. In this paper, DC-link voltage control to compensate the undesirable voltage deviation is proposed. Because control scheme considering SOC limit in LV networks have not been proposed, the proposed control scheme is novel. For validation of the proposed method, MATLAB/SimPowerSystems simulation tools are used. As a result of the simulation, the proposed control scheme is good for preventing voltage deviation.

References